

# On the accurate strain measurements for the crack initiation determination

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## Abstract

*Due to the huge demand for natural resources and minerals at a global scale, mining depths have progressively increased over the past decades to 1,000 m and deeper. However, despite many successes, deep mining operations are now facing new challenges never experienced before, including rock spalling and unwanted slabbing failures. This phenomenon is characterised as a sudden explosion-like fracture, which can affect the long-term viability and stability of deep underground mining. According to the literature, the most indicative predictor of the spalling strength at laboratory scale is the determination of the crack initiation point, which is defined as the onset of stress-induced damage in low-porosity rocks after the closure of pre-existing cracks. Hence, many methods have been developed to identify this critical design parameter, based mainly on the measurement of vertical, lateral or volumetric strains. That is, an accurate measurement of strain is deemed critical in determining the onset of the crack initiation threshold in the study of rock failure. Nevertheless, it remains difficult to determine the actual sample deformation in many geotechnical test apparatuses (i.e. multi-stage triaxial, Hoek cell, true triaxial, etc.), in which the measured deformation by linear variable differential transformers (LVDTs) is the cumulative deformation of the load frame itself, the loading platens, and the sample. As a result, relying on these deformation measurements can lead to erroneous estimation of the material's strain behaviour. This work presents a qualitative study on how to measure the actual sample deformation in a multi-functional true triaxial testing apparatus recently commissioned at the Geotechnical Engineering Centre (GEC) within the School of Civil Engineering at The University of Queensland (Brisbane, Australia).*

**Keywords:** *crack initiation threshold, spalling strength, strain measurement, true triaxial testing, strain gauges*

## 1 Introduction

Unlike shallow structures in rock, deep underground spaces are generally under true polyaxial stress conditions in terms of the major ( $\sigma_1$ ), intermediate ( $\sigma_2$ ) and minor principal stresses ( $\sigma_3$ ). The redistribution of such three-dimensional (3D) complex stress states around deep excavations is deemed to be the key factor driving rock failure as the depth increases (Duan et al. 2019). Particularly in brittle and low-porosity crystalline rocks under high stresses (i.e. in hard, intact rocks in an intact state near excavation boundaries), such 3D stresses could result in a sudden and spontaneous rock collapse accompanied by a huge energy release, which is commonly known as spalling or rockburst.

Rockburst occurs violently in the form of strainburst, fault slip, or pillar burst; or in less severe ejection, which is known as spalling or slabbing failure. The first recorded rock bursting in history was in 1738 in the British tin mine in Stafford (Guo et al. 2003). In the early 1900s, this phenomenon came into sight and brought more attention (Blake & Hedley 2003). Since then, incidents have been recorded in many places around the globe such as Sweden, Australia, Norway, Japan, USA, South Africa, Canada, China and Brazil (Martna 1972; Hargraves 1980; Selmer-Olsen 1988; Fujii et al. 1997; Whyatt et al. 2002; Brown & Hudyma 2017;

Wang 2018). There are over 23 countries in which the rockburst phenomenon has been observed, including France, Russia, Ukraine, and others (Zhu et al. 2019). Australia is within the top five countries in the world in the mining industry, according to Geoscience Australia, with over 350 mines operating in the country (Youwei et al. 2018). Since the early 1900s, mining-induced seismicity and related rockburst have been reported in a number of Australian mines, and particularly in recent years, these issues have become of serious concerns for the safety of versatile Australian mines and have constrained their economic viability (Potvin et al. 2000). The global mining industry market reached 800 billion dollars in 2019 (PWC Australia 2019). Therefore, solving the challenges related to this sector attracts global attention. Simulating the rock behaviour under actual true triaxial in situ conditions can expand our knowledge about rock failure and therefore facilitate the way we act to avoid such incidents.

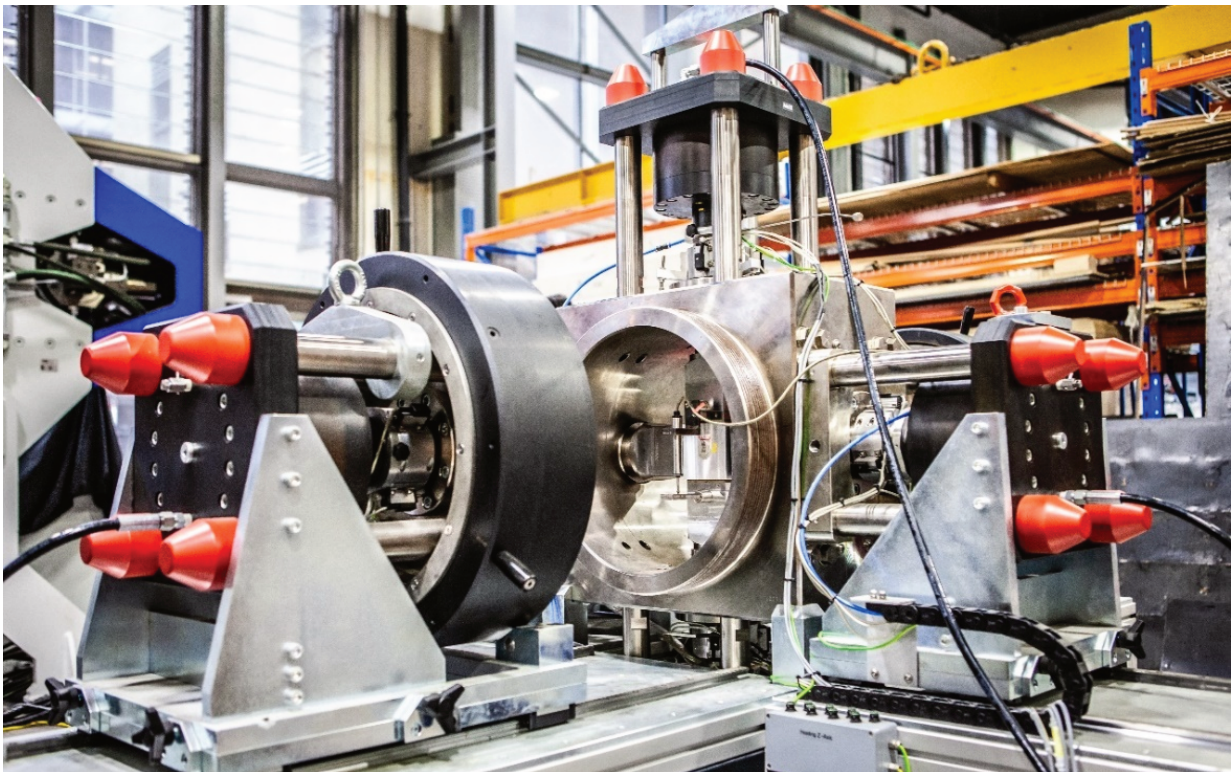
While rockburst and spalling are commonly related to high stresses at depth in hard rock, sudden brittle failures could also happen in weaker rocks at shallow depth, in lightly cemented sandstones and in clay shales under low confinement (Kaiser & Kim 2008); e.g. incidents have been reported at Kundana, Bounty, Mt Charlotte, Big Bell and Kanowna Belle operations at depths of 300–600 m. Nevertheless, when the mining depth approaches and exceeds 1,000 m, the ratio of intact rock strength to the induced stresses around an excavation triggers the failure of the rock almost immediately after excavation (Kusui & Villaescusa 2016). Similar to rockburst, spalling is closely related to the propagation and coalescence of internal tension cracks surrounding the rock (Gong et al. 2018; Bahaaddini et al. 2019). Recent research suggests that the crack initiation stress level, which is the first stage of stress-induced damage, can be used reliably as a parameter to estimate the in situ spalling strength around underground excavations in massive to moderately jointed, brittle, low-porosity rocks (Nicksiar & Martin 2012). From this point of view, various methods have been proposed to identify the crack initiation threshold at laboratory scale. Given that most of the available methods utilise volumetric, lateral or axial strain as a benchmark to define the crack initiation point (Brace et al. 1966; Lajtai 1974; Stacey 1981; Martin & Chandler 1994; Diederichs 2007; Nicksiar & Martin 2012), the accurate measurement of strain in a loaded rock becomes a critical issue for the correct prediction of the in situ spalling strength.

Measuring the actual sample strain thoroughly is challenging, since most of the displacement sensors mounted on commercially available load application systems (i.e. multi-stage triaxial, Hoek cell, and true triaxial load frames) provide a combined strain measurement of the load frame itself (i.e. the metal platens) plus the rock specimen. Therefore, the strain of the metal platens should always be subtracted in the first instance using preliminary calibration charts to avoid an overestimation of the sample's true deformation (Silva et al. 2019). Alternatively, direct measurement methods through strain gauging technique can be adopted. However, given that strain gauges are relatively expensive and non-reusable, it could make the overall cost of the experimentation more expensive (Silva et al. 2019). Further, it has been shown that the direct measurement of sample deformation under three-dimensional stress conditions is extremely difficult in practice. With these motivations in mind, this study presents a systematic approach to determine the actual sample deformation under true triaxial testing conditions by subtracting the machine LVDT readings from the load cell deformation.

The true triaxial testing system designed by Mogi (1970) was the first one that enabled the application of three independent and uniform loads to rock samples (Li et al. 2012; Serati et al. 2020). Following Mogi's work, different types of true triaxial testing systems have been designed and fabricated to investigate rock behaviour under uniaxial, biaxial and true triaxial stress states (Aseyeva et al. 1987; Takahashi & Koide 1989; Chang & Haimson 2000; Kwasniewski et al. 2003; He et al. 2007; Ingraham et al. 2013; Kun et al. 2016). The simulation of rock behaviour in natural slopes, open pit mines, and road cuttings has been carried out successfully by adopting different stress paths in a true triaxial apparatus (Kun et al. 2016). Over 100 true triaxial testing machines (TTT) are reported in the literature to investigate the behaviour of soil, concrete, and rock under different loading conditions (Shi et al. 2012). According to Takahashi et al. (2001), TTTs can be classified based on the loading method into: type I – rigid loading in all three directions, type II – flexible loading in all three directions, and type III – a combination of both. Most of the available TTTs are of type III. Some drawbacks were detected in previous generations of TTTs, as summarised in the literature, such as

loading eccentricity, loading gap, end friction effect and the accurate measurement of volume change (Shi et al. 2012, Feng et al. 2016).

More recently, the Geotechnical Engineering Centre (GEC) within the School of Civil Engineering at The University of Queensland in collaboration with Wille Geotechnik in Germany has designed and fabricated a state-of-the-art TTT system composed of three main units: hydraulic unit (hydraulic pack), pressure intensifiers (X, Y, Z), and loading frame (Figure 1). The system is configured to test three cubic sizes of 50, 100 and 200 mm. The maximum applied pressure on all three orthogonal directions (X, Y, Z) is 21 MPa stress on the largest 200 mm cubic specimens (or up to 340 MPa on 50 mm cubic samples). It is equipped with an elevated temperature facility (up to 100° C), with humidity control in which a thermo-mechanical model can be developed. The system is capable of testing both saturated and unsaturated samples and is designed to accommodate the addition of monitoring equipment, including acoustic emission and ultrasonics, for the assessment of progressive damage processes (Mutaz et al. 2019). The system can also perform rock permeability testing at up to 10 MPa pressure and hydraulic fracturing at up to 52 MPa in three directions.



**Figure 1** The University of Queensland true triaxial testing system (after Mutaz et al. 2019)

## 2 Experimental testing

### 2.1 Testing plan

In order to measure the actual sample deformation, the following equipment was used in this study:

- 10 MN Material Testing System (MTS) and 1 MN MTS compression machines.
- 100 mm aluminium 7075-T6 reference cube equipped with high-tech strain gauges.
- 50 mm reference cubes (aluminium 7075-T6, MACOR ceramic glass, stainless steel AISI 302).
- Two 100 mm external displacement sensors (AMETEK DFG 2.5).
- Two 50 mm external displacement sensors (Solartron Metrology).
- High-tech strain gauges.

The mechanical properties of the standard cubes are given in Table 1, while the high-tech strain gauge characteristics are given in Table 2. The calibration curves of both external displacement sensors are shown in Figure 2. The following steps were adopted in order to measure the cell deformation and hence the actual deformation of the sample:

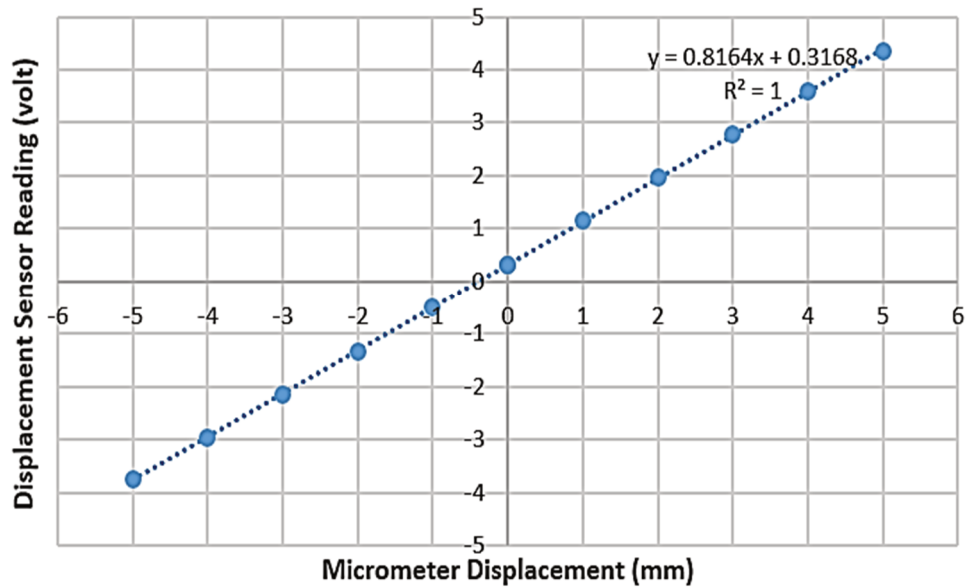
- Attaching the high-tech strain gauges to the standard cubes to measure their deformation at the centre by assuming the cubes will deform similarly at the mid, top and bottom points.
- Testing the standard cubes using an MTS loading frame under different loading conditions and measuring the central sample deformation via strain gauges and the overall sample deformation through external displacement sensors fixed across the sample.
- Testing the standard cubes using the TTT system under the same loading conditions as the MTS loading frame and measuring the central sample deformation using the strain gauges, while the overall displacements were measured using the mounted LVDTs of the true triaxial.
- The strain measurement of the strain gauges was used to measure the material's elastic parameters; elastic modulus and Poisson's ratio.
- Comparing the results of the strain gauges in both loading frames under the same loading conditions to indicate the accuracy of the force measurement in the newly developed TTT system.
- Consequently, the TTT deformation was calculated by subtracting the readings of the external displacement sensors on the MTS loading frame from the true triaxial LVDT readings.

**Table 1 Mechanical properties of the standard cubes**

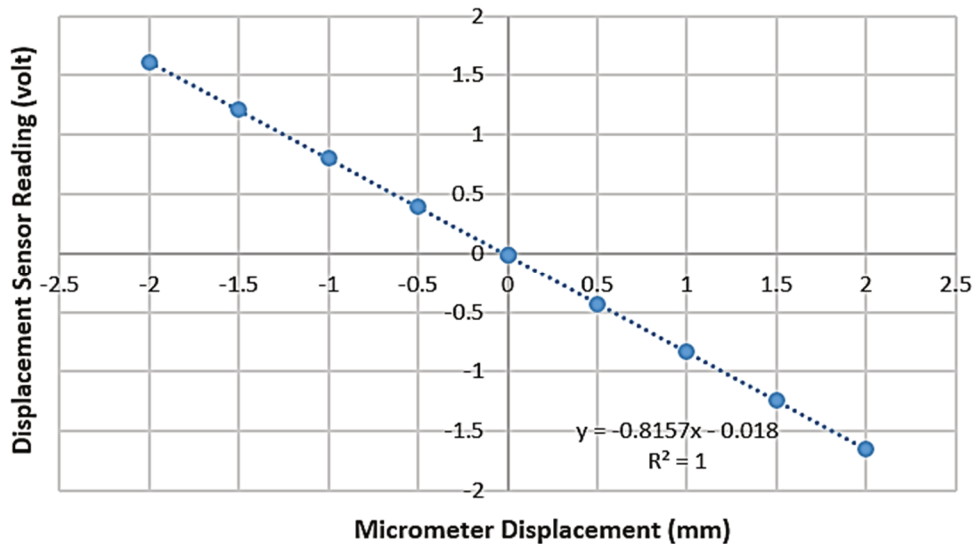
Cube type	Elastic modulus (E) (GPa)	Poisson's ratio ( $\nu$ )
Aluminium (7075-T6)	71.7	0.33
MACOR ceramic glass	66.9	0.29
Stainless steel AISI 302	180	0.29

**Table 2 Strain gauge characteristics**

Design parameter	Reference datasheet
Strain gauges type	FCAB-5-8
Adhesive type	P-2
Coefficient of thermal expansion	$8.1 \times 10^{-6}/^{\circ}\text{C}$
Temperature coefficient	$+0.1 \pm 0.05\%/10^{\circ}\text{C}$
Tolerance	$\pm 0.85 [(\mu\text{m}/\text{m})/^{\circ}\text{C}]$



(a)



(b)

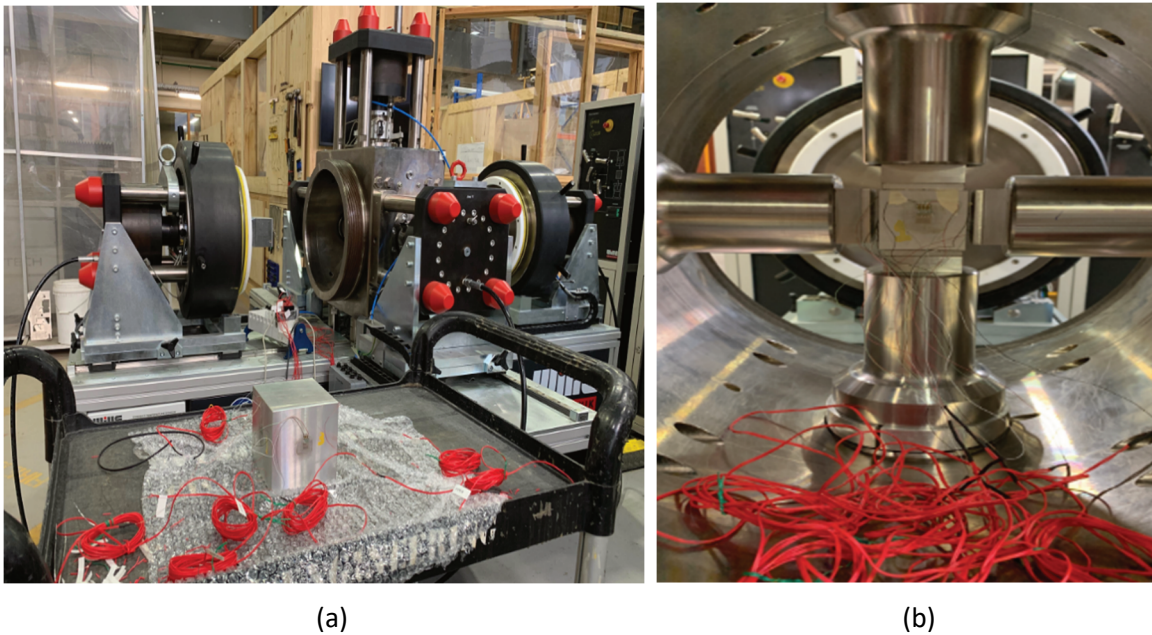
**Figure 2 Calibration curves of the external displacement sensors: (a) 100 mm AMETEK DFG 2.5; (b) 50 mm Solartron Metrology**

## 2.2 Elastic parameter measurement

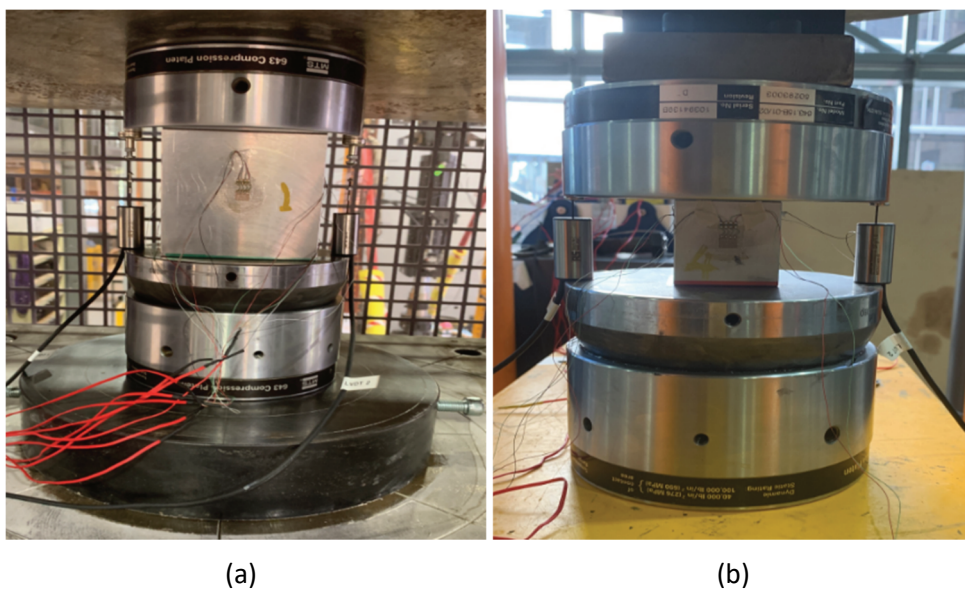
All strain gauges were glued at the centre of the sample and the strain signals were recorded by NI 9236 and NI 9235 modules. The analogue outputs of the external displacement sensors were recorded by a module NI 9215 with 16-bit resolution, resulting in  $0.37 \mu\text{m}$  displacement resolution. To ensure proper contact between the cubes and the loading platens, a constant seating pressure was maintained before each test; i.e. 7–12% of the maximum applied load. Table 3 presents the designated loading condition throughout the whole process. The configuration of the samples inside the TTT and the MTS loading frames is shown in Figures 3 and 4; respectively.

**Table 3 Designated loading condition**

Cube type	Cube size (mm)	Loading rates (kN/min)	Maximum load (kN)	Maximum pressure (MPa)
Aluminium	100 × 100	50, 100, 200, 300, 400, 500, 600	666	66
Aluminium Ceramic Steel	50 × 50	50, 100, 200, 300, 400	400	160



**Figure 3 Sample positioned inside the true triaxial loading cell for: (a) 100 mm cube (after Mutaz et al. 2019); (b) 50 mm cube**



**Figure 4 The external displacement sensors positioned inside: (a) 10 MN MTS for 100 mm cube (after Mutaz et al. 2019); (b) 1 MN MTS for 50 mm cube**

Under the same loading conditions, but different loading rates, the variation of strain gauge readings between the MTS loading frame and the TTT system was very small (less than 0.003 mm or a strain value of 0.00003%) for the tested cubes. Figures 5 and 6 present the relative difference between the strain gauge reading in the MTS and TTT systems for 100 and 50 mm aluminium cubes, respectively, under different loading and loading rates. This finding provides evidence of the accuracy of the loading measurement in the TTT system.

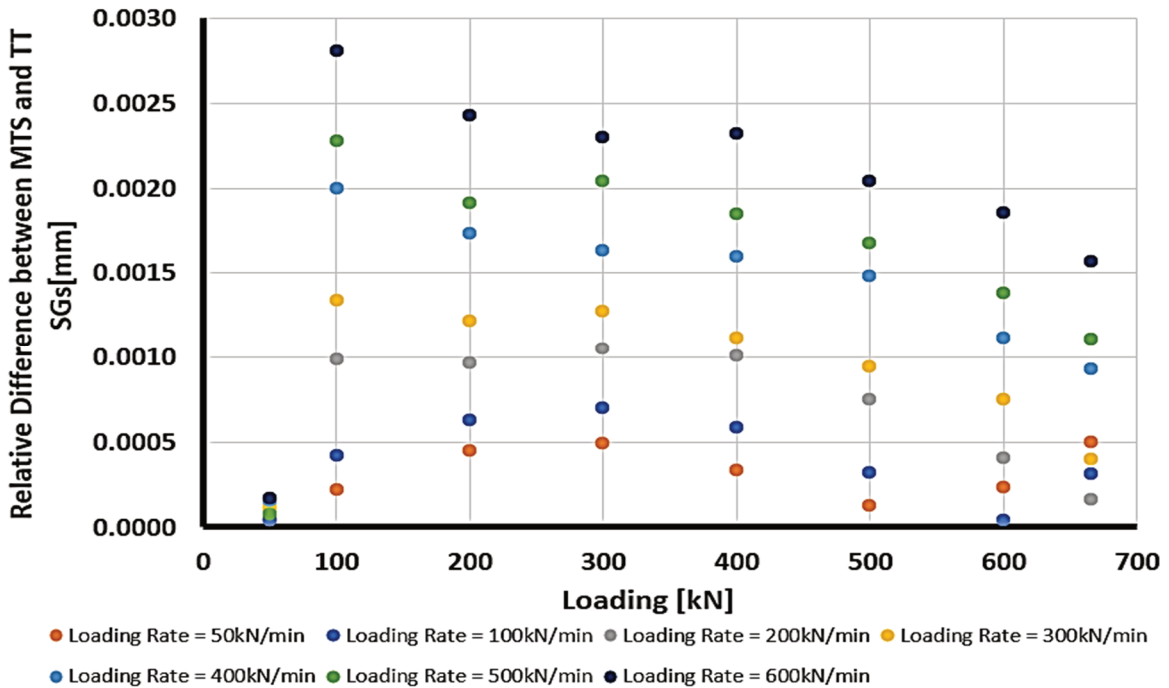


Figure 5 Relative difference of strain gauge readings between MTS and true triaxial for 100 mm aluminium cube

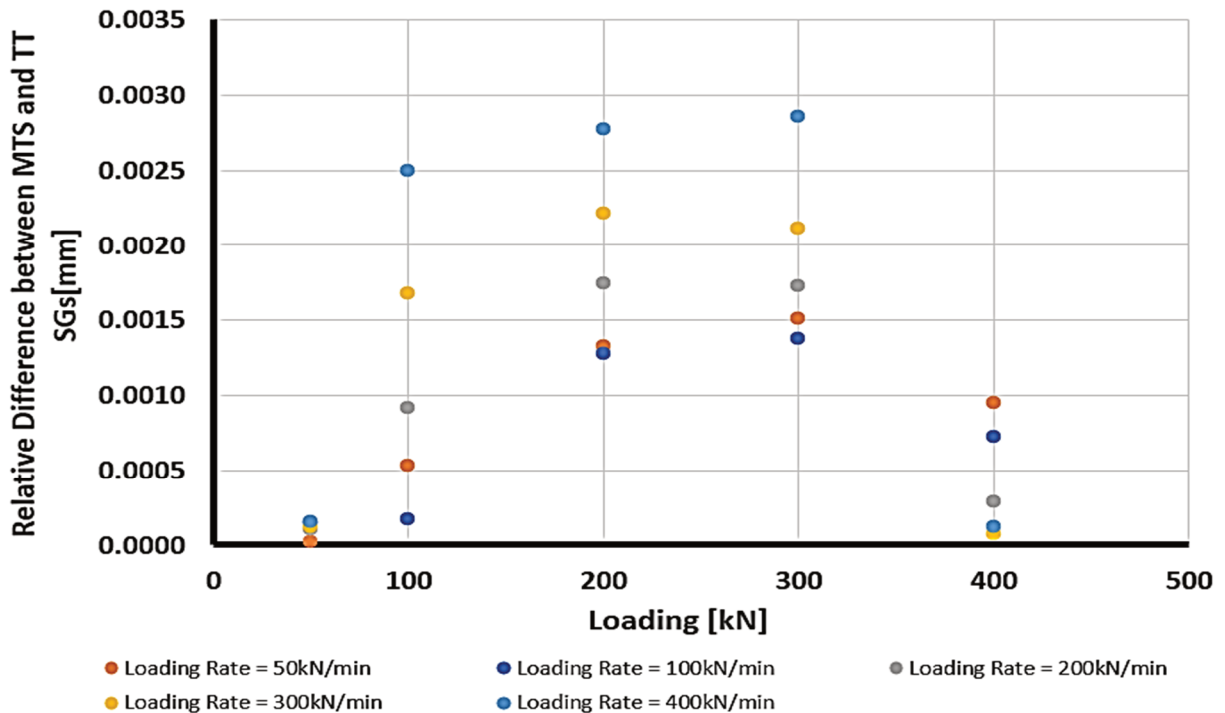


Figure 6 Relative difference of strain gauge readings between MTS and true triaxial for 50 mm aluminium cube

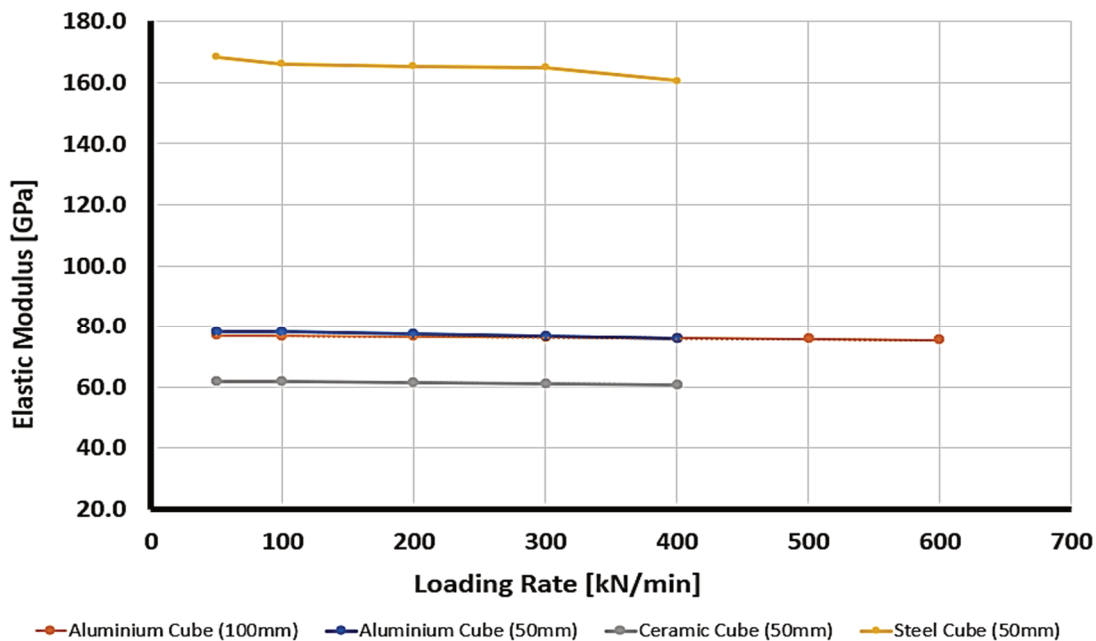
Martin & Chandler (1994) proposed that the crack threshold stress can also be calculated by measuring the so-called crack volumetric strain  $(\Delta V/V)_{cr}$ , which is defined by subtracting the elastic volumetric strain  $(\Delta V/V)_{el}$  from the total volumetric strains  $(\Delta V/V)$  in a triaxial testing condition, or:

$$\left(\frac{\Delta V}{V}\right)_{cr} = \left(\frac{\Delta V}{V}\right)_{total} - \left(\frac{\Delta V}{V}\right)_{el} \tag{1}$$

It can readily be shown that the value of elastic volumetric strain is related to the material’s Young’s modulus and Poisson’s ratio according to:

$$\left(\frac{\Delta V}{V}\right)_{el} = \frac{2\nu-1}{E}(\sigma_1 + 2\sigma_3) \tag{2}$$

That is, the accurate determination of Young’s modulus (elastic modulus) and Poisson’s ratio could also have a great impact on the measurement of the crack initiation point. The variation of the elastic modulus for different material types under different loading conditions is presented in Figure 7. The relative error in measuring the elastic modulus by using the TTT is in the range of 5.0–9.0% for aluminium, ceramic and steel cubes. The logic behind this relatively low error is that the measurement of strain has been considered at the centre of the sample using the centrally located strain gauges.



**Figure 7** Variation of measured elastic modulus through true triaxial at different loading rates

### 2.3 Cell deformation

The main aim of this study is to measure the cell deformation, which is equivalent to the overall displacement of the loading cell and loading platens. Since the LVDTs of the TTT are mounted on the ram piston, they measure the overall deformation of the cell plus the actual sample deformation. The external displacement sensors that are attached along the cubes in the MTS loading frame (Figure 4) were used to determine the actual sample deformation across its full length. Therefore, the cell deformation can be calculated by subtracting the displacement of the true triaxial LVDTs that are mounted on the true triaxial ram piston from the displacement of the external displacement sensors on the MTS loading frame, to give:

$$D_{cell} = D_{TT\ LVDT} - D_{MTS\ DS} \tag{3}$$

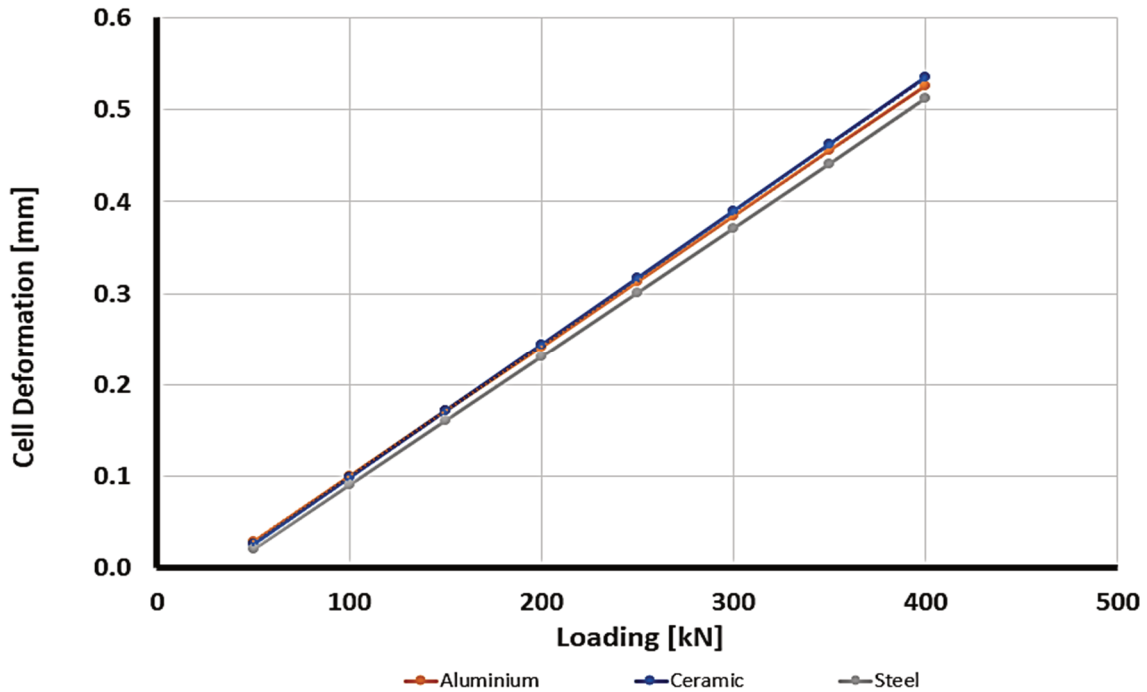
where:

$D_{TT\ LVDT}$  = the true triaxial LVDT readings.

$D_{MTS\ DS}$  = the displacement readings from the external displacement sensors of the MTS.



The cell deformation has been calculated for all the three reference cubes (aluminium, ceramic and steel) as illustrated in Figure 8. It can be deduced that the cell deformation is an intrinsic property of the cell material itself and is solely a function of the applied load. In other words, the cell deformation (on each axis) is independent of the rock/sample being tested inside the loading frame and is only a function of the material of the loading frame and the applied stress level (Figure 8).



**Figure 8 True triaxial cell deformation for aluminium, ceramic and steel, on the Z axis**

However, in a TTT system, different components of the machine transfer the load onto the sample in each axis. Therefore, it is important to measure the cell deformation in all directions (major, intermediate and minor principal stresses). The cell deformation was calculated for each axis (X, Y and Z) using the 50 mm aluminium reference cube (Figure 9). Table 4 summarises the cell deformation equations in all three axes. The load cell deformation in all three axes is not the same, but can be given as a function of the applied load as given in Table 4.

**Table 4 Cell deformation equations in all three axes for 50 mm standard aluminium cube**

Z axis	Y axis	X axis
$y = 0.0016 x - 0.0751$	$y = 0.0014 x - 0.0756$	$y = 0.0013 x - 0.067$

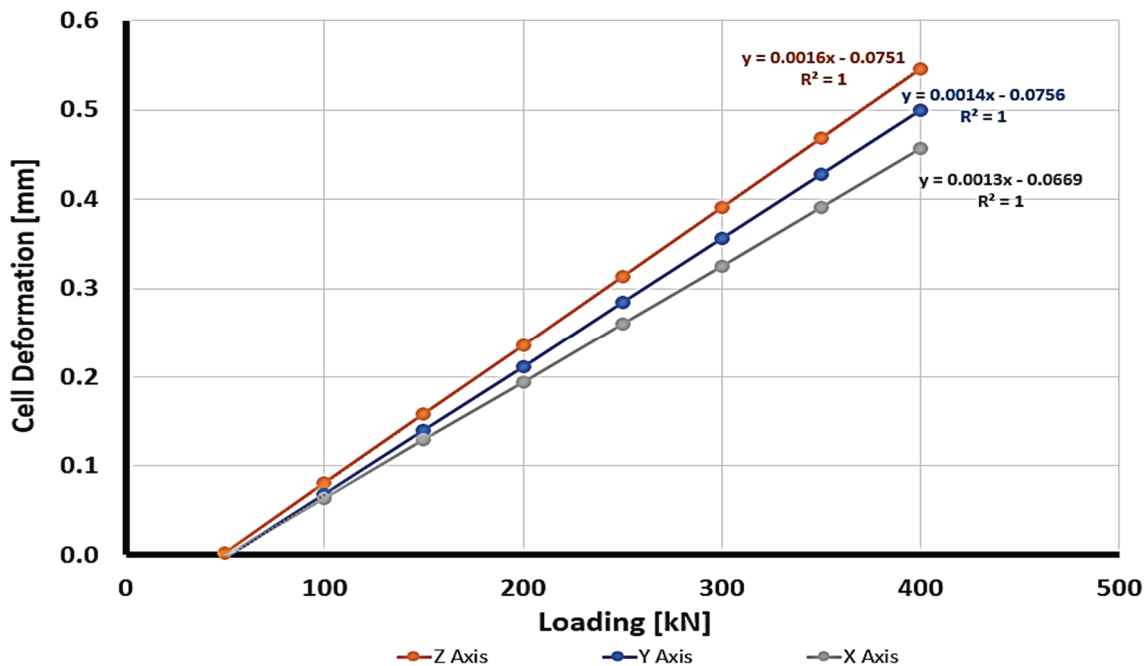


Figure 9 Cell deformation of true triaxial for 50 mm aluminium cube in all three stress directions

### 3 Conclusion

The increasing depth of mining is associated with many problems, such as underground rock spalling and rockburst. A proper prediction of the in situ spalling strength plays a vital role in preventing catastrophic damage to deep underground mines. True triaxial testing systems have been used widely to characterise, model and predict the in situ spalling strength. Recent research shows that spalling failure is likely to occur when the induced stresses trigger the onset of cracks. The literature is replete with many models to predict crack initiation based on stress-strain response. However, most of the displacement sensors that are mounted on TTT machines measure the overall displacement of the loading cell plus the actual sample deformation. Dismissing the actual sample deformation and relying only on the loading frame displacement can result in an inaccurate measurement of the material's strain and hence affect the accurate prediction of the in situ spalling strength. This work was aimed at assessing a testing procedure to measure the actual sample deformation without the need for further strain gauging.

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